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2.6.1 gives a simple derivation of the joint distribution of the sample mean and sample variance of a normal data sample.

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Chapter 1 - Introduction to Probability
Theory. This chapter provides an overview
of the probability theory. To master both
the model building and the subsequent

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analysis of the probability models, one must have certain knowledge of basic probability theory. The chapter presents an experiment where the sample space is S .

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Chapter 1. 1. $S = \{ (R,R), (R,G), (R,B), (G,R), (G,G), (G,B), (B,R), (B,G), (B,B) \}$

The probability of each point in S is $1/9$.

$S = \{ (e_1, e_2, \dots, e_n), n \geq 2 \}$ where $e_i \in \{ \text{heads, tails} \}$.

In addition, $e_n = e_{n-1} = \text{heads}$ and

for $i = 1, \dots, n-2$ if $e_i = \text{heads}$, then $e_{i+1} = \text{tails}$.

$P \{ 4 \text{ tosses} \} = P \{ (t,t,h,h) \} + P \{ (h,t,h,h) \} =$

2.

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Exercise 8 (Bonferroni's inequality) From the inclusion/exclusion identity for two sets we have $P(E \cap F) = P(E) + P(F) - P(EF)$.

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Theory 1.1 Probability Model The three

basic components of a probability model:
sample space, events, and probability of
events. 1.1.1 Sample Space Definition 1.1

The set of all outcomes of an experiment
is called the sample space and is denoted
by S .

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Causality connotes lawlike necessity,
whereas probabilities connote

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exceptionality, doubt, and lack of
regularity. Still, there are two compelling
reasons for starting with, and in fact
stress, probabilistic analysis of
causality; one is fairly straightforward, the
other more subtle.

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